

FIG. 1A

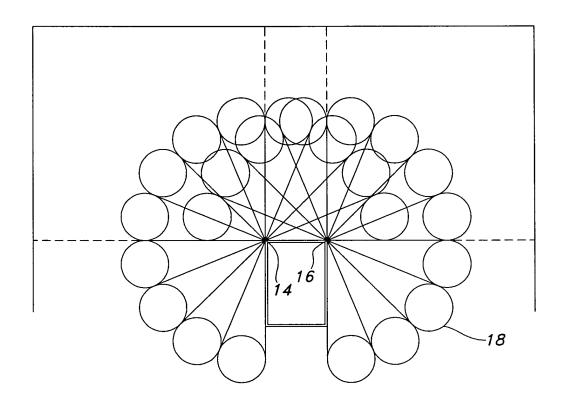


FIG. 1B



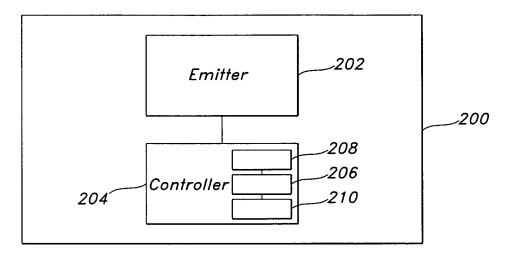


FIG. 2A

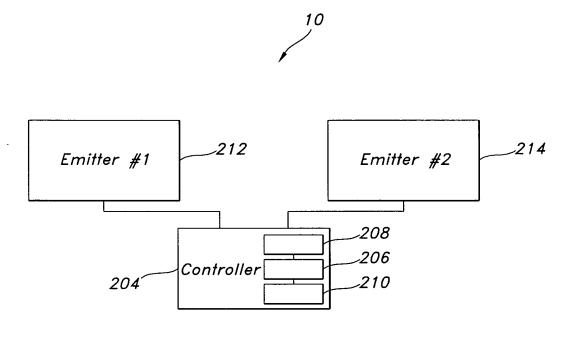
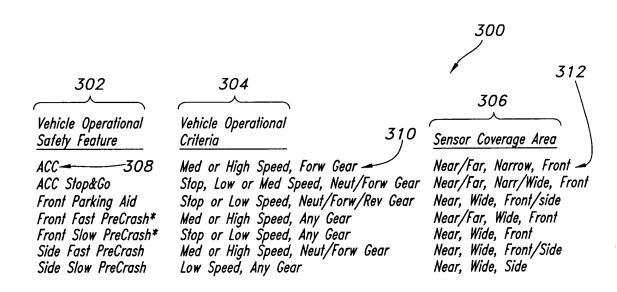


FIG. 2B



*Includes Frontal Collision Warning and Pedestrian Detection Features

FIG. 3

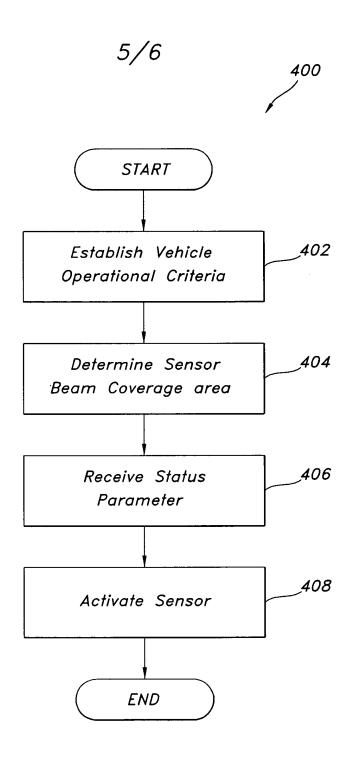


FIG. 4

Shared Sensor Modes

When Gear = Park

Front PreCrash(Auto) + Side Slow PreCrash(Auto)

When Speed = Stopped, and Gear = Neutral or Forward

- Front PreCrash(Auto) + Side Slow PreCrash(Auto) + Front Parking Aid(Auto)
- Front PreCrash(Auto) + Side Slow PreCrash(Auto) + Front Parking Aid(Auto) + ACC Stop&Go (Comm)

When Speed = Stopped, and Gear = Reverse

• Front PreCrash(Auto) + Side Slow PreCrash(Auto) + Front Parking Aid(Auto)

When Speed = Low Speed, and Gear = Neutral or Forward

- Front PreCrash(Auto) + Side Slow PreCrash(Auto) + Front Parking Aid(Auto)
- Front PreCrash(Auto) + Side Slow PreCrash(Auto) + Front Parking Aid(Auto) + ACC Stop&Go (Comm)

When Speed = Low Speed, and Gear = Reverse

• Front PreCrash(Auto) + Side Slow PreCrash(Auto) + Front Parking Aid(Auto)

When Speed = Medium Speed

- Front PreCrash (Auto) + Side Fast PreCrash (Auto)
- Front PreCrash (Auto) + Side Fast PreCrash (Auto) + ACC (Comm)
- Front PreCrash (Auto) + Side Fast PreCrash (Auto) + ACC Stop&Go (Comm)
- Front PreCrash (Auto) + Side Fast PreCrash (Auto) + ACC (Comm) + ACC Stop&Go (Comm)

When Speed = High Speed

- Front PreCrash (Auto) + Side Fast PreCrash (Auto)
- Front PreCrash (Auto) + Side Fast PreCrash (Auto) + ACC (Comm)

Auto = Automatic (Feature operates if criteria are met)

Comm = Commanded (Feature operates if criteria are met and operator has commanded)

FIG. 5